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First Look 3.1 System

Classi fi cations and

Properties 2.1.1

Introduction In this

module some of the basic

classi fi cations of systems

will be brie fl y

introduced and the most

important properties of

these systems are

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explained. As can be
seen, the properties of

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Here the input $x(t)$ is the
transmitted signal and
the output $y(t)$ is the

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received signal. Assume
the message is

represented in binary
format and that a “ 1 ”
is communicated in an
interval of length T by
transmitting the symbol
 $p(t)$ depicted in Fig.

P2.41 (b) in the pertinent
interval and that a “ 0 ”
is communicated by
transmitting $-p(t) \dots$

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“ The signal value at any time n is 1.97 times the signal value at the previous time $[n-1]$ minus the signal value at the time before that! $[n - 2]$. ” ! If we know the signal value at any two times, we can compute its ! value at all other (discrete) times. This is quite similar to a ! second-

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equation for which
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More seriously, signals are functions of time (continuous-time signals) or sequences in time (discrete-time signals) that presumably represent quantities of interest. Systems are operators that accept a given signal (the input

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signal) and produce a new signal (the output signal). Of course, this is an abstraction of the processing of a signal.

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is a function representing a physical quantity or variable, and typically it contains information about the behaviour or nature of the phenomenon.

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